

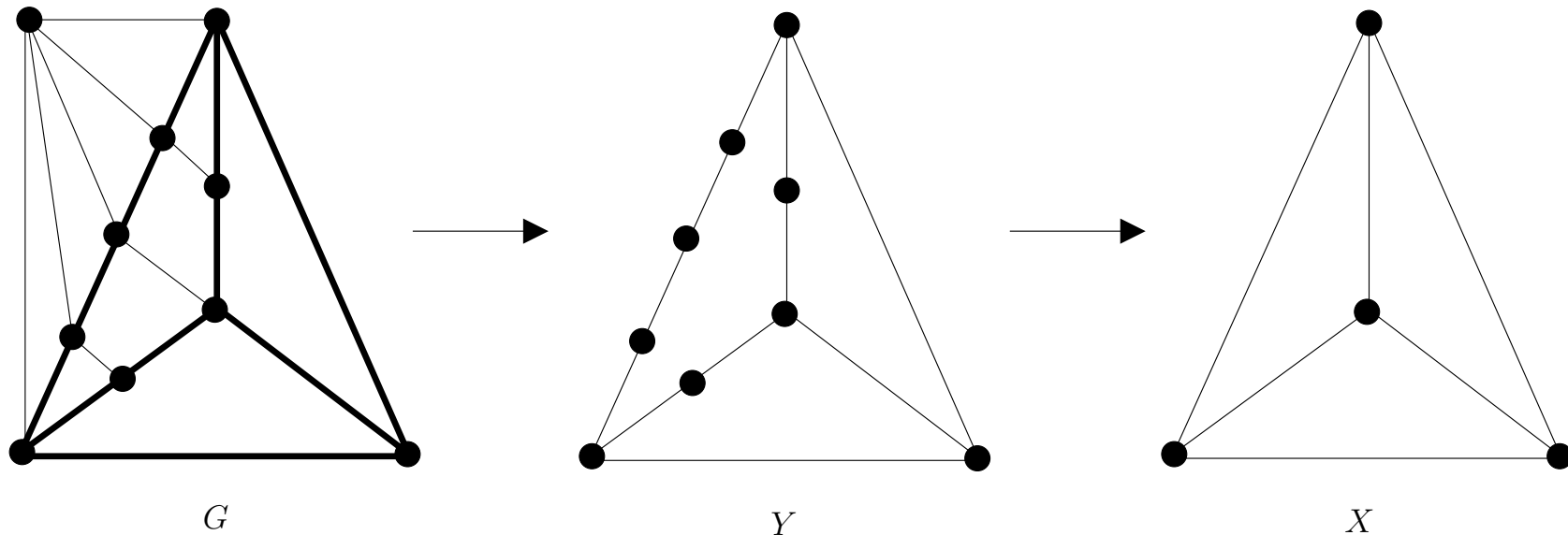
Topological containment in graphs: New characterizations from computer search

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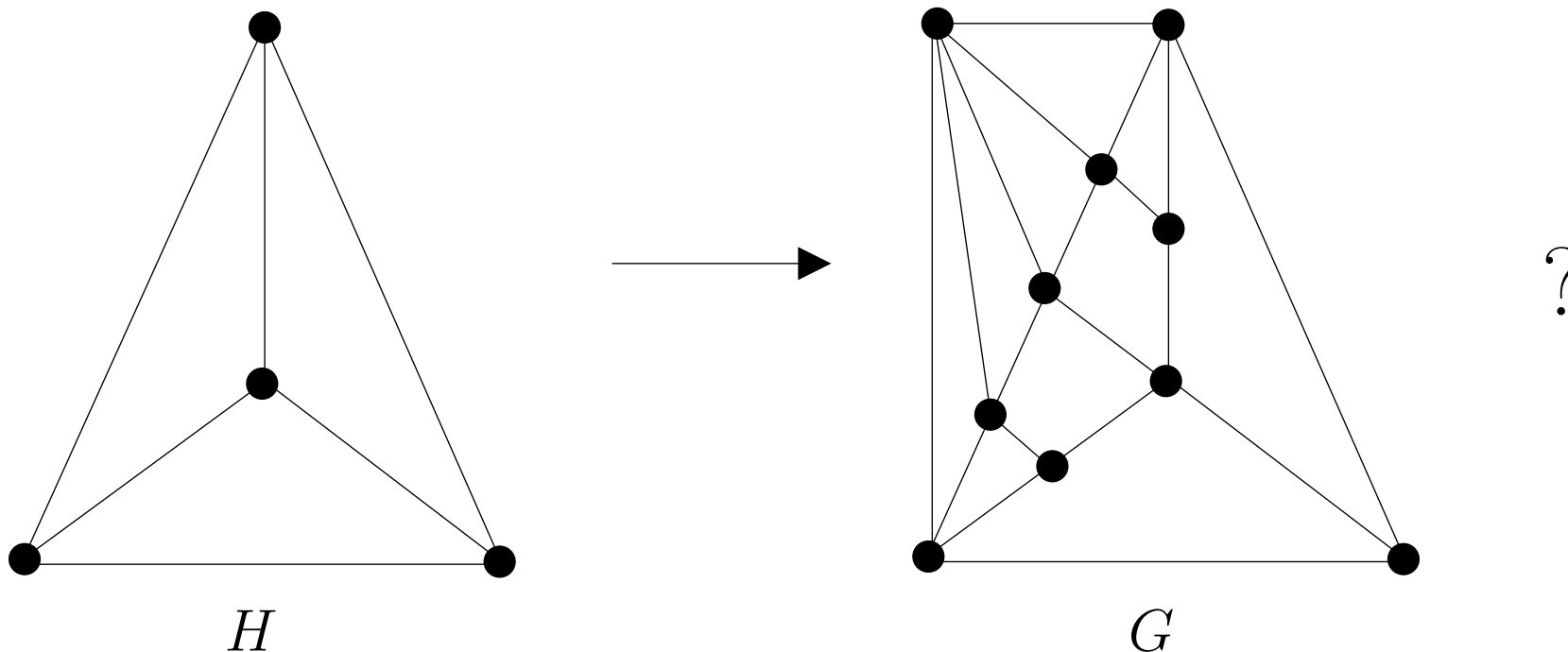
1 Topological containment



- Formally: G topologically contains X iff G contains some subgraph Y such that X can be obtained from Y by performing a series of contractions limited to edges that have at least one endvertex of degree 2.
- Also: Y is an X -subdivision; G contains an X -subdivision

Problem of topological containment:

- $TC(H)$: For some fixed *pattern graph* H — given a graph G , does G contain an H -subdivision?



2 Robertson and Seymour results

DISJOINT PATHS (DP)

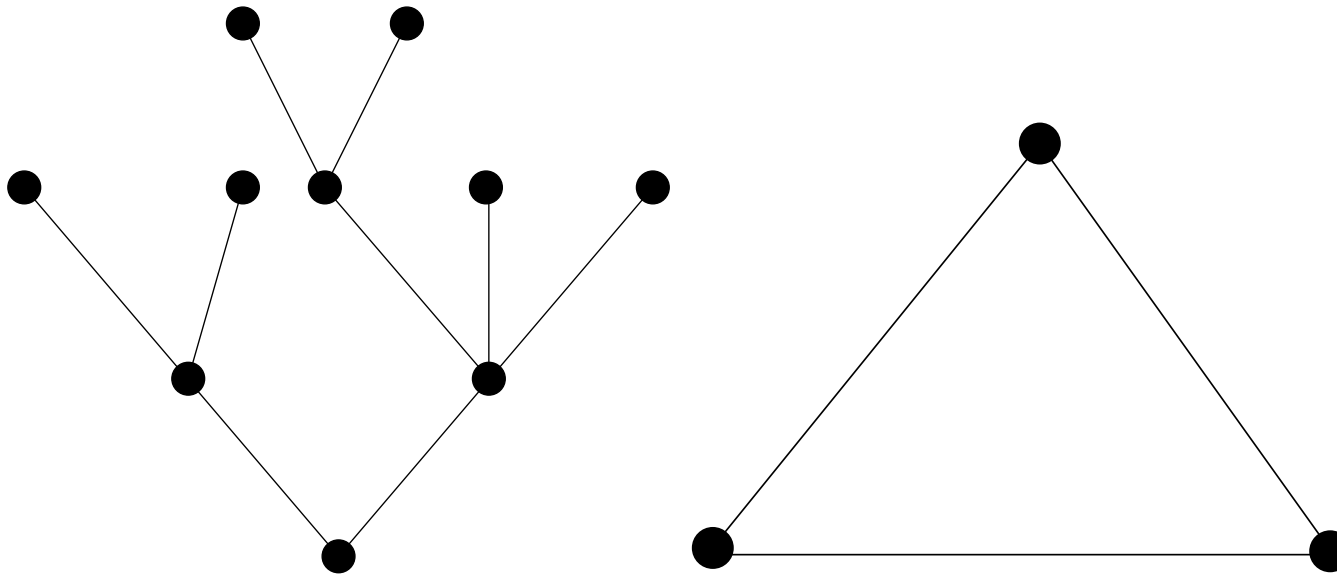
Input: Graph G ; pairs $(s_1, t_1), \dots, (s_k, t_k)$ of vertices of G .

Question: Do there exist paths P_1, \dots, P_k of G , mutually vertex-disjoint, such that P_i joins s_i and t_i ($1 \leq i \leq k$)?

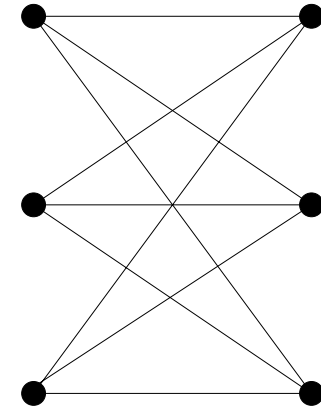
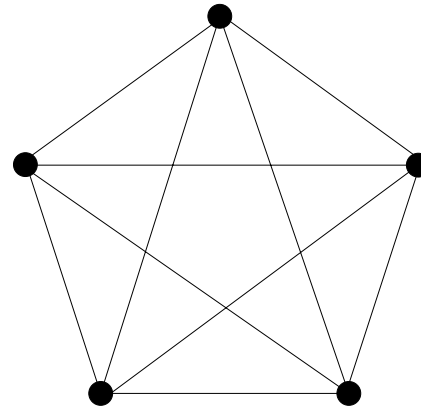
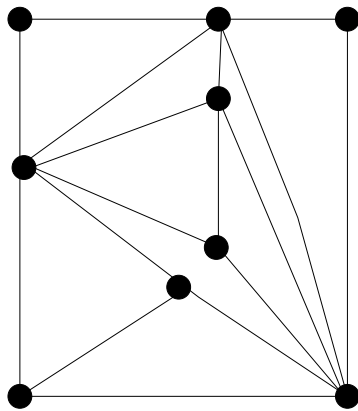
- DISJOINT PATHS is in P for any fixed k .
- This implies topological containment problem for fixed H is also in P — use DP repeatedly.
- We know p-time algorithms must exist for topological containment, but practical algorithms not given — huge constants.
- Finding efficient, practical algorithms for particular pattern graphs is still an important task.

3 Examples of good characterizations

- Trees — K_3

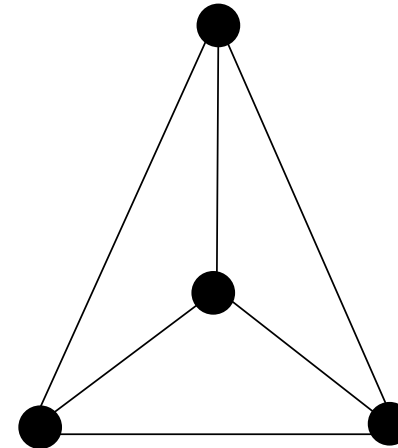
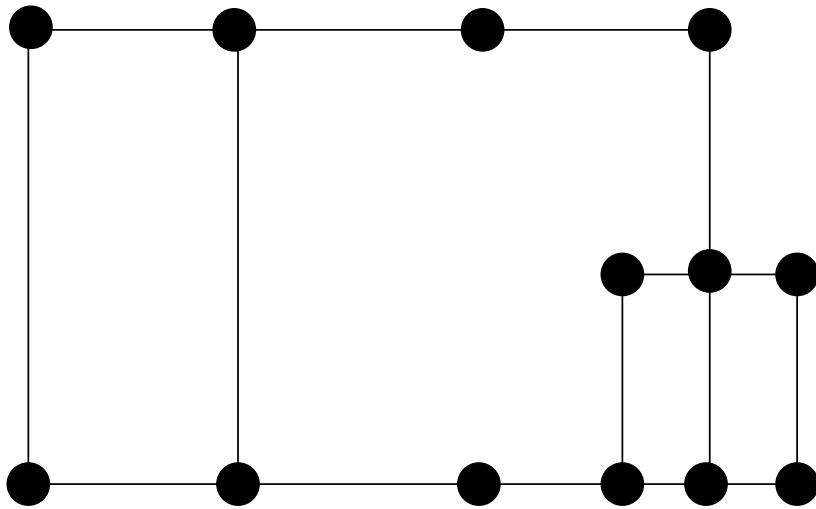


- Kuratowski (1930) — K_5 or $K_{3,3}$ in non-planar graphs



- Wagner (1937) and Hall (1943) strengthened this result to characterize graphs with no $K_{3,3}$ -subdivisions

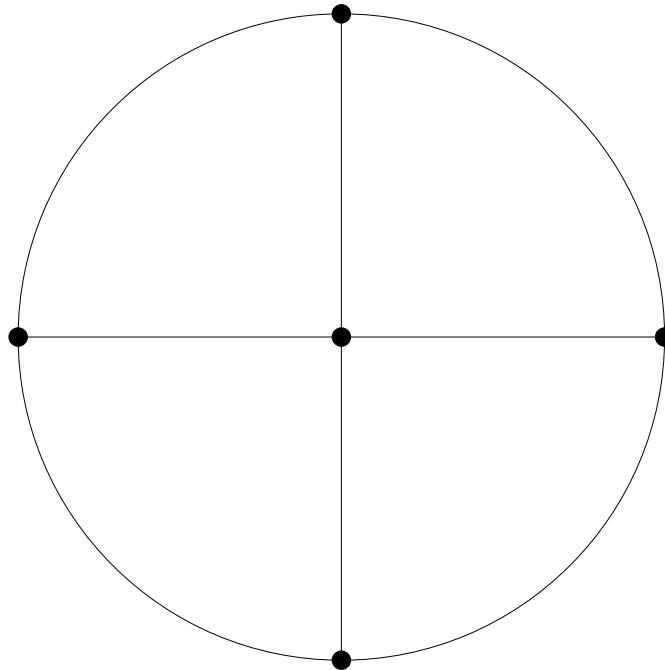
- Duffin (1965) — K_4 in non-series-parallel graphs



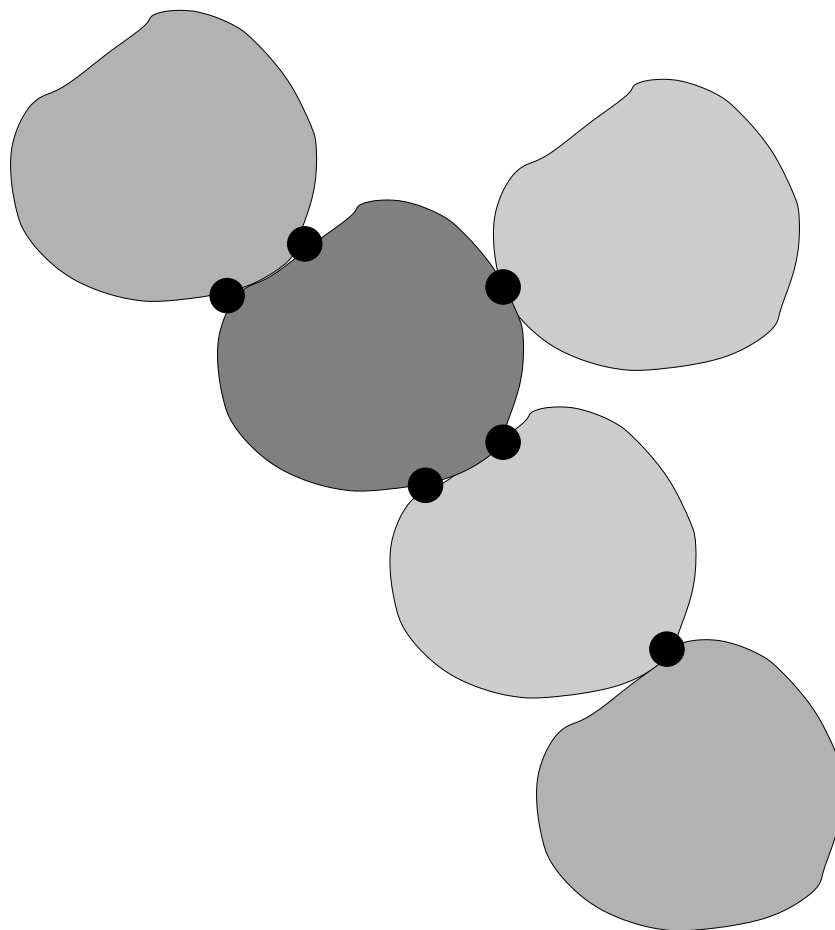
4 Previous results on wheel subdivisions

4.1 W_4 — wheel with four spokes

- Farr (1988) — If G is 3-connected, G contains a W_4 -subdivision if and only if G has a vertex of degree ≥ 4



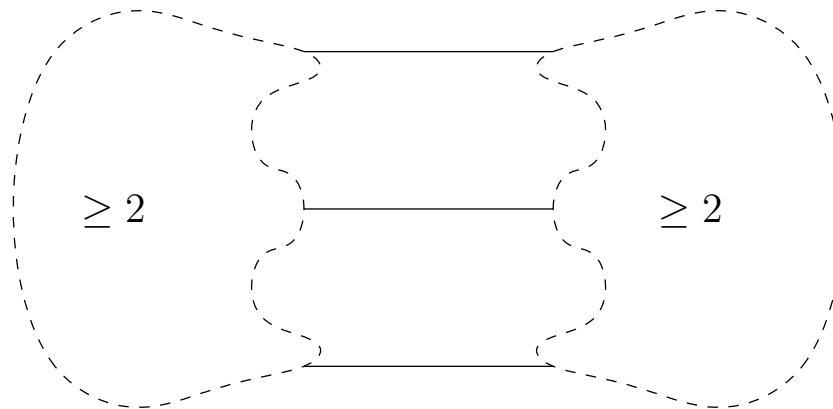
Structure of graphs with no W_4 -subdivisions



4.2 W_5 — wheel with five spokes

Theorem (Farr, 88).

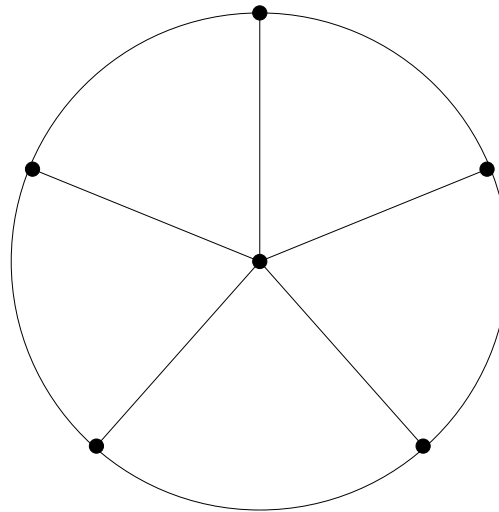
Let G be 3-connected, with no **internal 3-edge-cutset** ...



Internal 3-edge-cutset

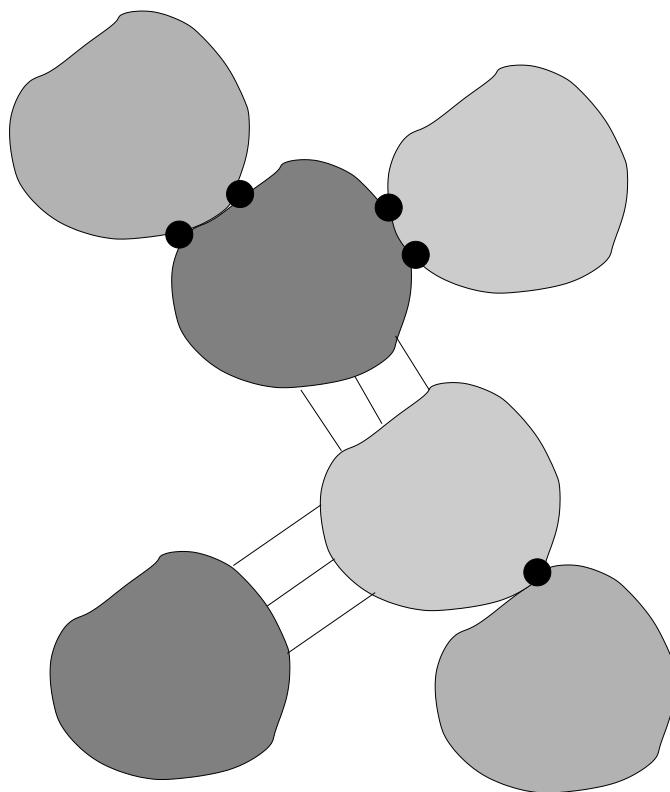
Theorem (Farr, 88).

Let G be 3-connected, with no internal 3-edge-cutset. Then G has a W_5 -subdivision if and only if G has a vertex v of degree at least 5 and a circuit of size at least 5 which does not contain v .



W_5 : wheel with five spokes

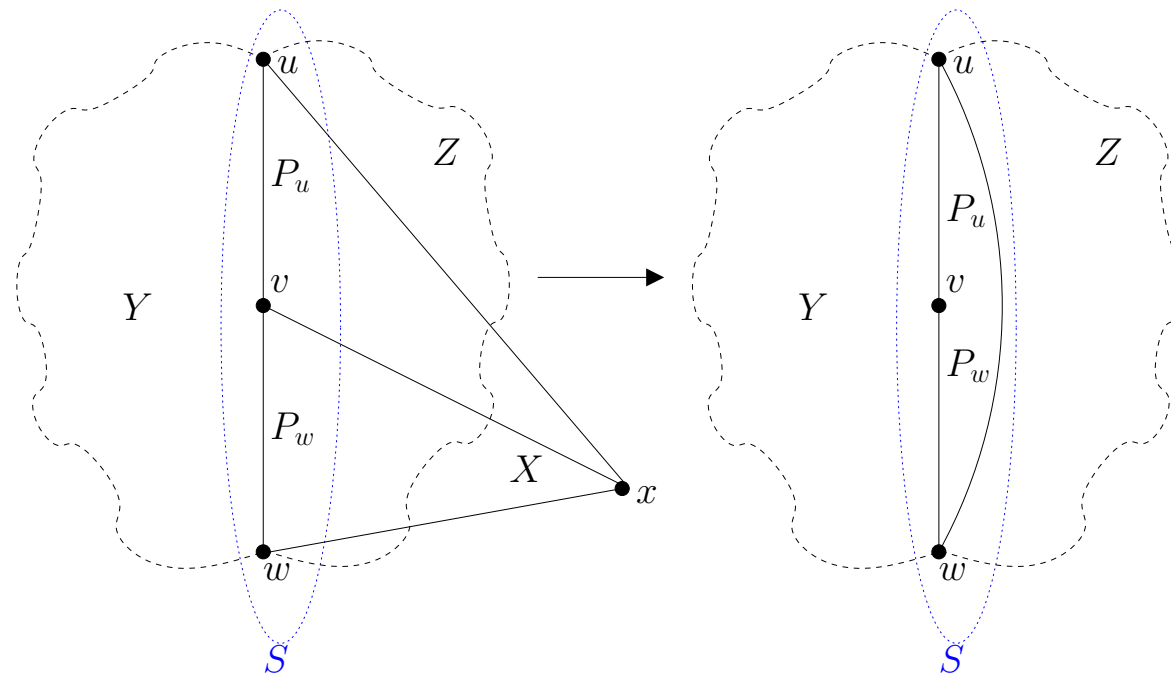
Structure of graphs with no W_5 -subdivisions



5 Strengthened W_5 result

- Uses a forbidden reduction

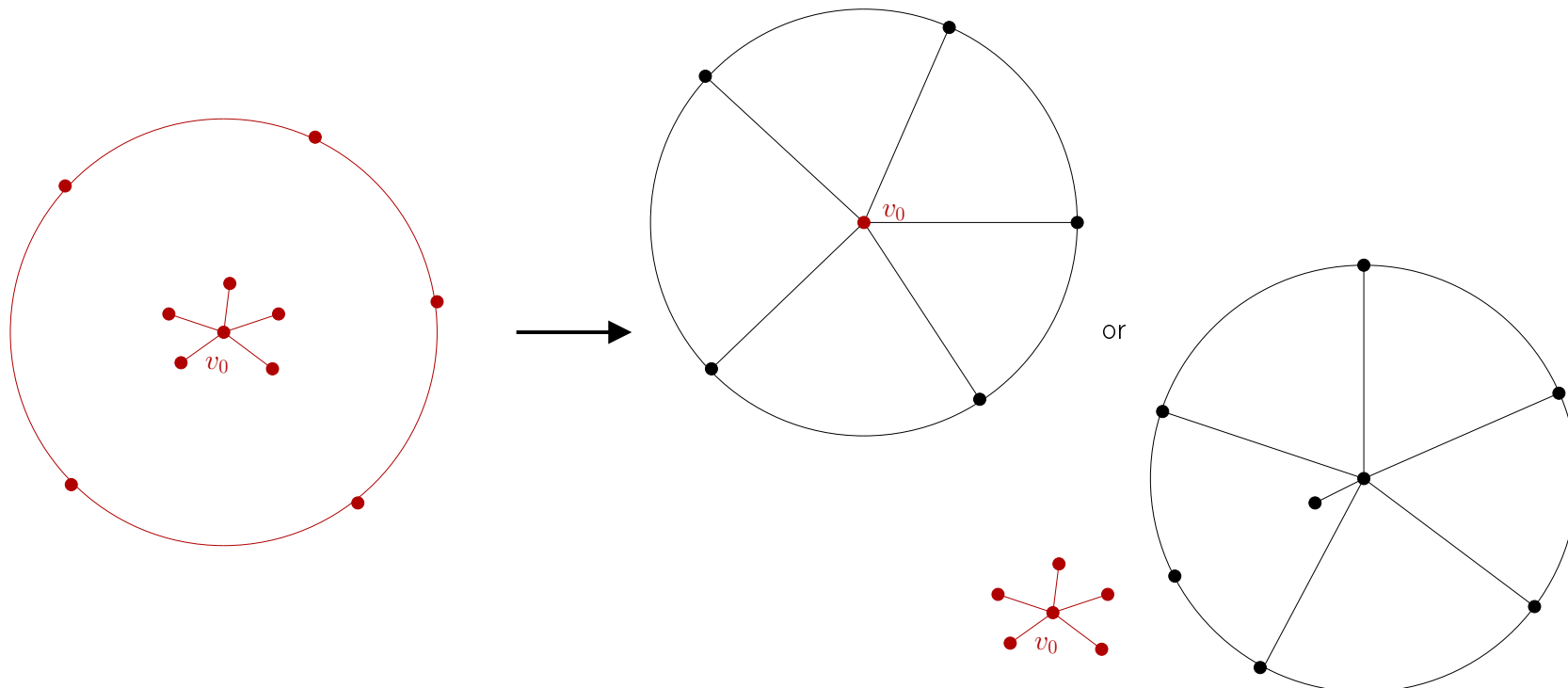
Reduction 1A



- X , Y , and Z are *bridges* of $G|S$.

Theorem.

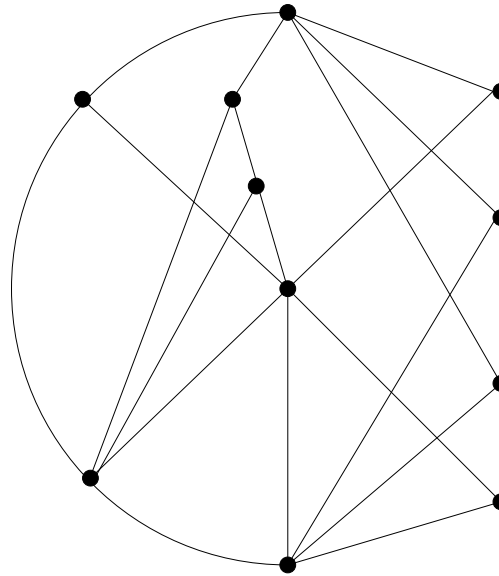
Let G be a 3-connected graph, with no internal 3-edge-cutset, such that Reduction 1A cannot be performed on G . Let v_0 be a vertex of degree ≥ 5 in G . Suppose there is a cycle of size at least 5 in G which does not contain v_0 . Then either G has a W_5 -subdivision centred on v_0 , or G has a W_5 -subdivision centred on some vertex v_1 of degree ≥ 6 , with a rim of size at least 6.



6 Characterization of graphs with no W_6 -subdivision

Theorem.

*Let G be a 3-connected graph that is not topologically contained in the **graph A** ...*

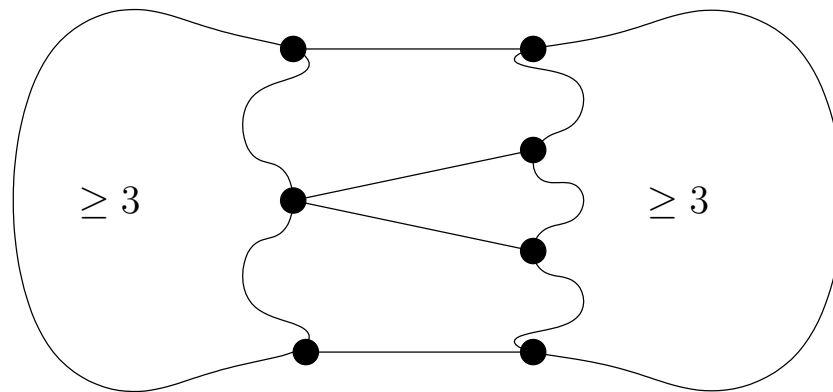


Graph A

Theorem.

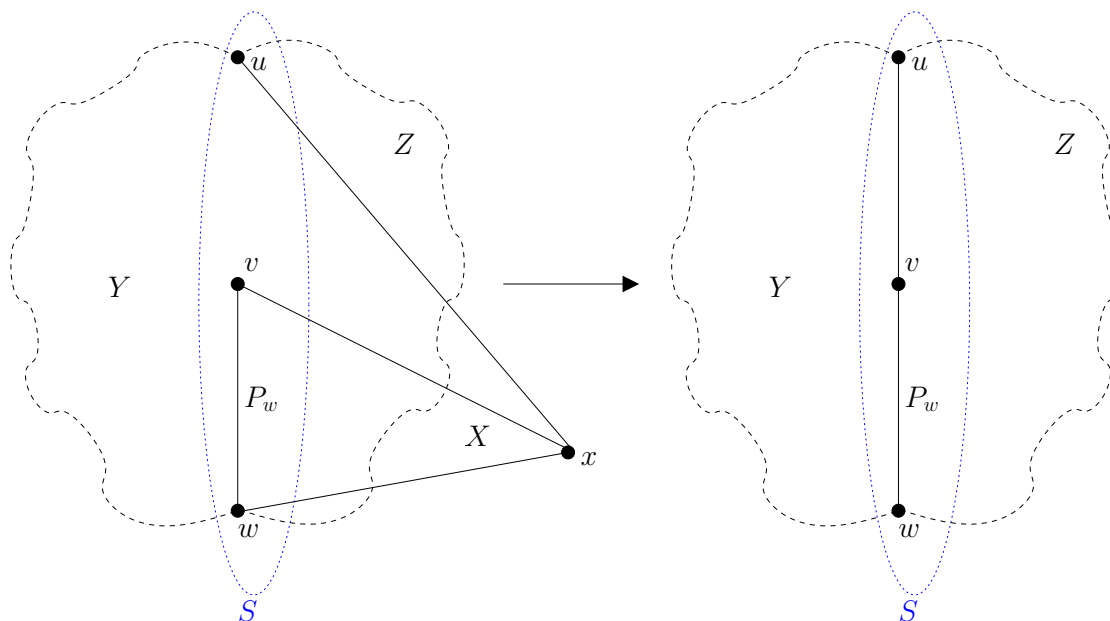
Let G be a 3-connected graph that is not topologically contained in the graph A .

Suppose G has no internal 3-edge-cutsets, no **internal 4-edge-cutsets** . . .



Theorem.

Let G be a 3-connected graph that is not topologically contained in the graph A . Suppose G has no internal 3-edge-cutsets, no internal 4-edge-cutsets, and is a graph on which neither Reduction 1A nor **Reduction 2A** can be performed, for $k = 6 \dots$

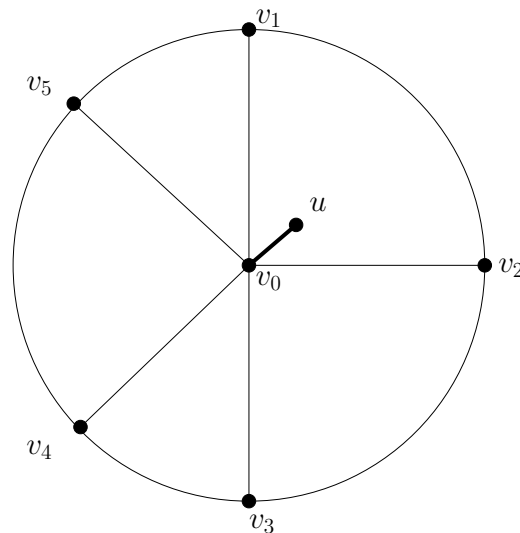


Theorem.

Let G be a 3-connected graph that is not topologically contained in the graph A . Suppose G has no internal 3-edge-cutsets, no internal 4-edge-cutsets, and is a graph on which neither Reduction 1A nor Reduction 2A can be performed, for $k = 6$. Then G has a W_6 -subdivision if and only if G has a vertex v of degree at least 6.

Proof — a summary.

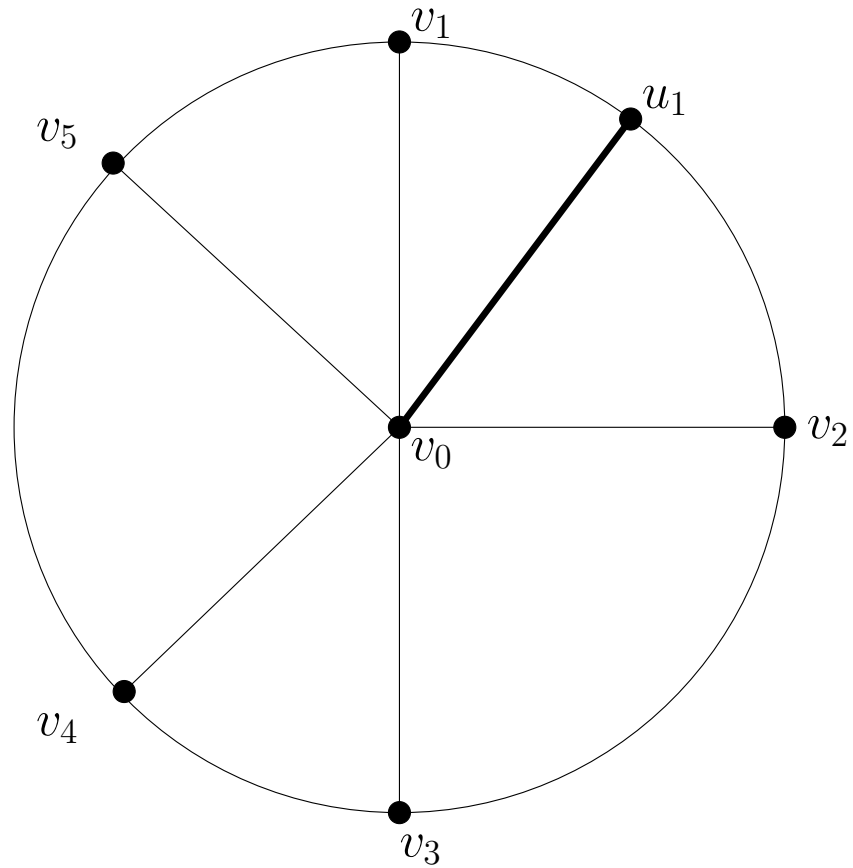
- Suppose the conditions of the hypothesis hold for some graph G .
- By the strengthened W_5 result above, there exists some vertex v_0 of degree ≥ 6 in G that has a W_5 -subdivision H centred on it.



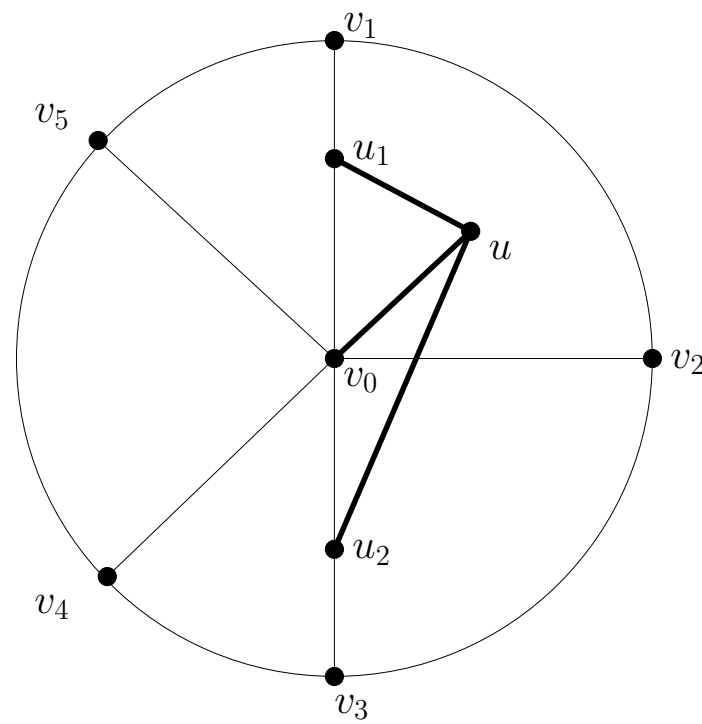
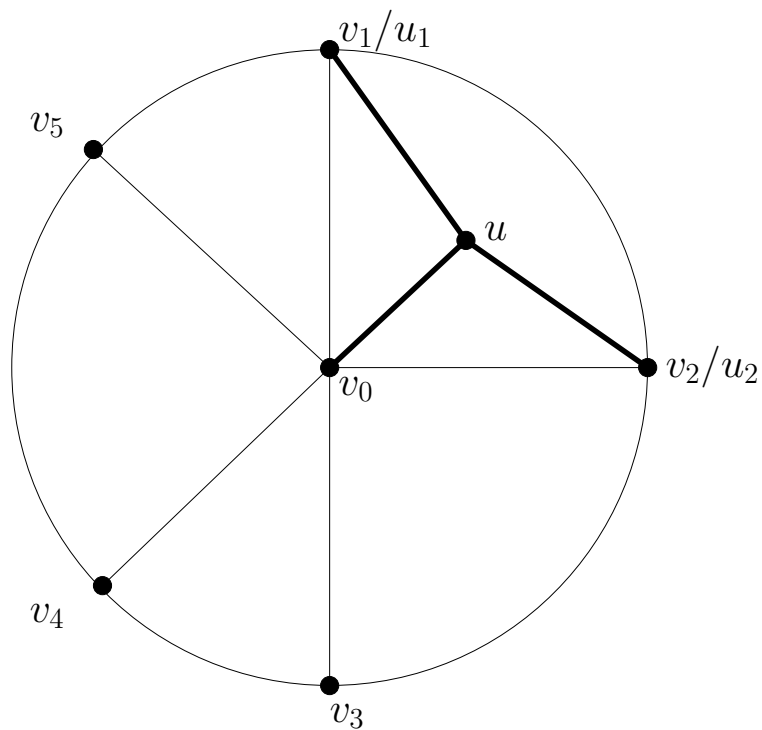
- How does u connect to the rest of H in order to preserve 3-connectivity?

Three possibilities:

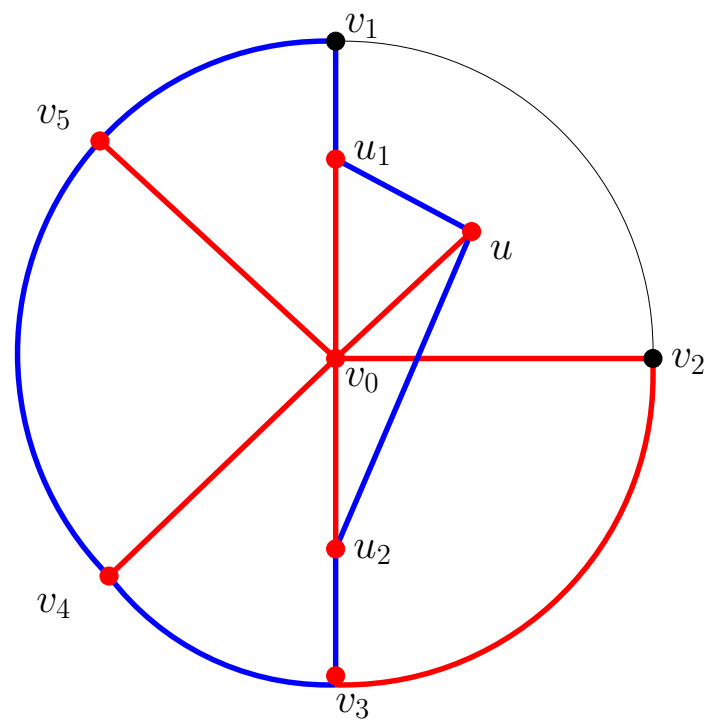
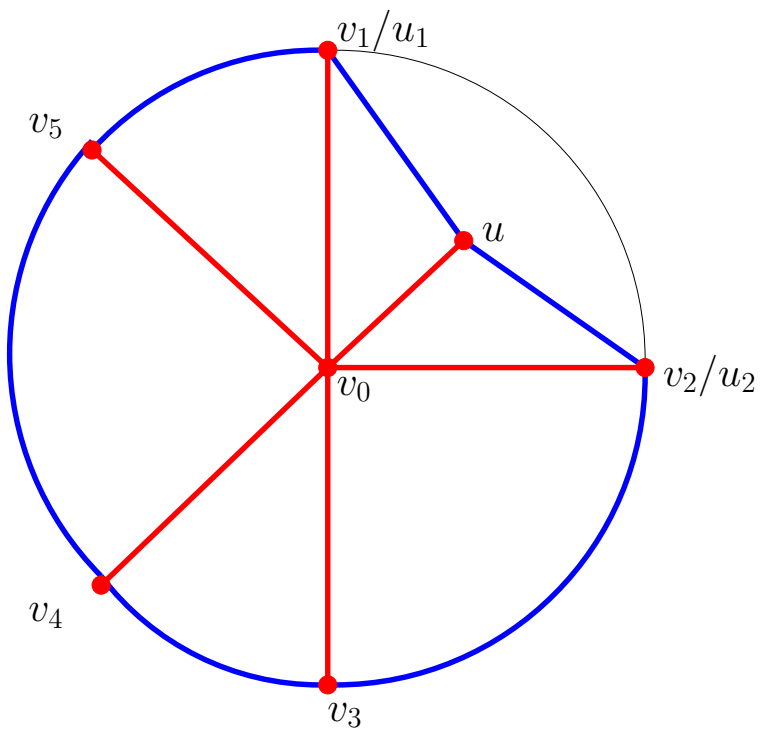
- (a) Path from v_0 to some vertex u_1 on the rim of the W_5 -subdivision, not meeting any spoke.



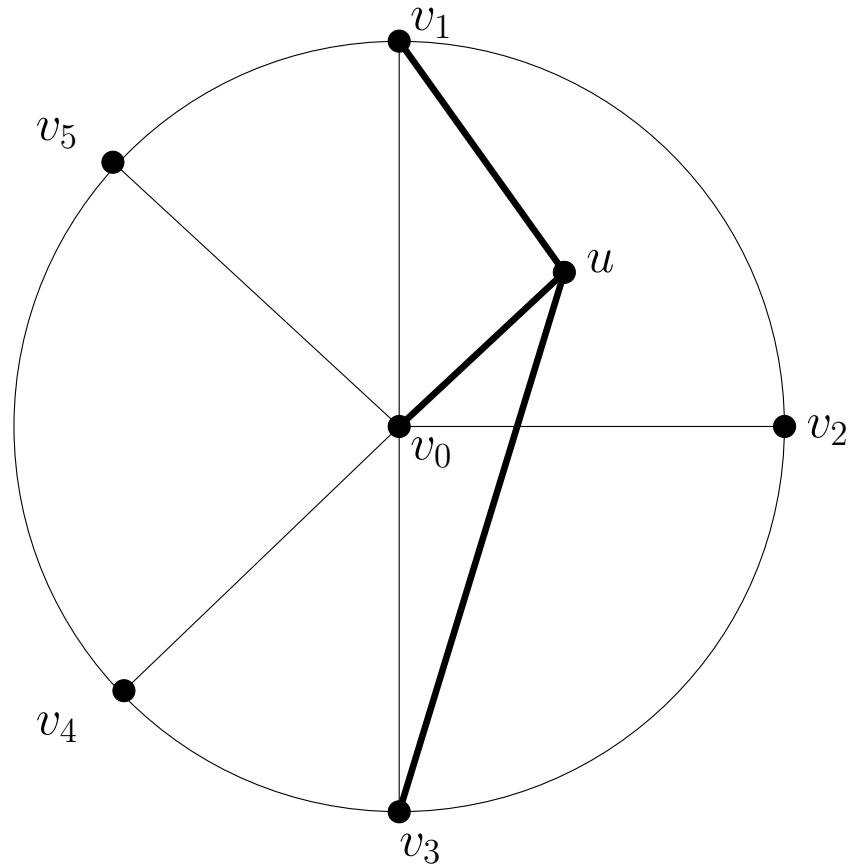
(b) Two paths from u to two separate spokes of H .



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- Dealing with one particular case takes up the majority of the proof:

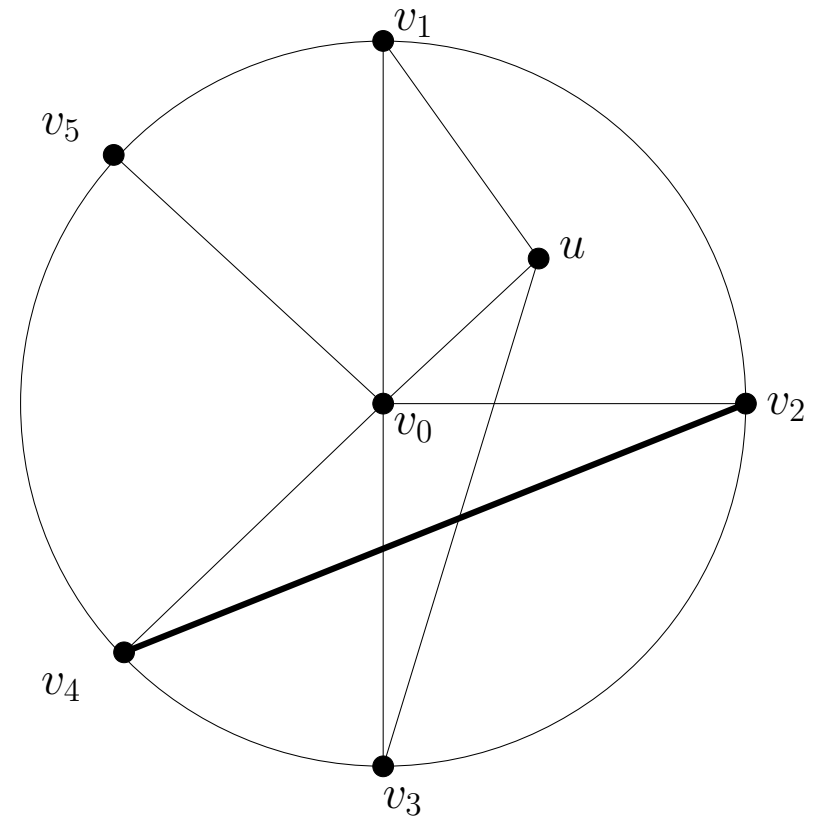
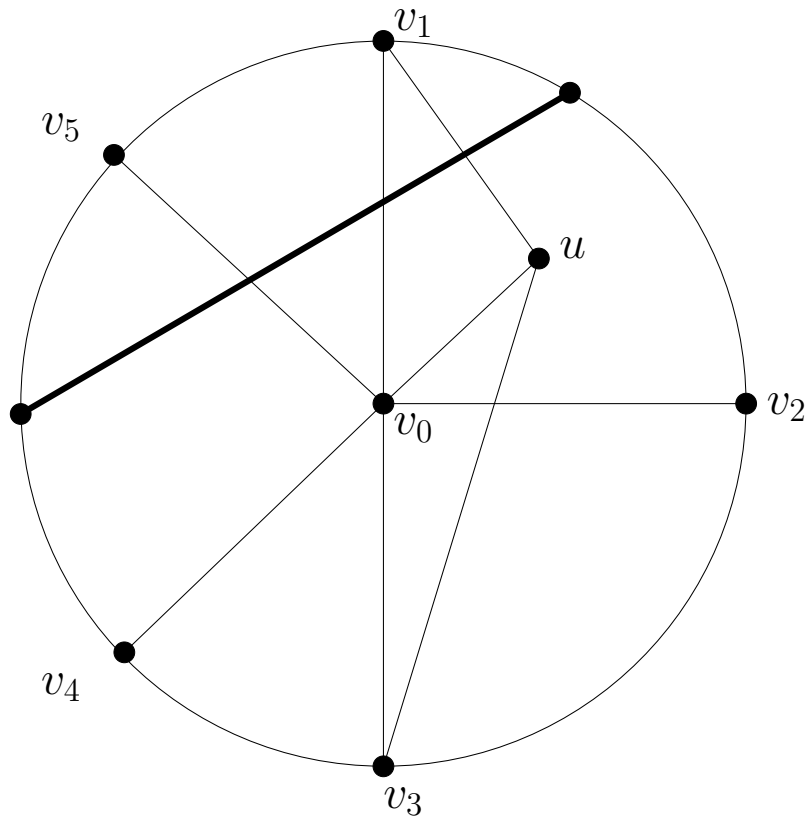


- This graph meets 3-connectivity requirements, but Reduction 1A can be performed on it.
- So there must be more structure to the graph.
- More in-depth case analysis required, based on different ways of adding this structure.
- Program developed in C to automate parts of this analysis; parts of proof depend on results generated by this program.

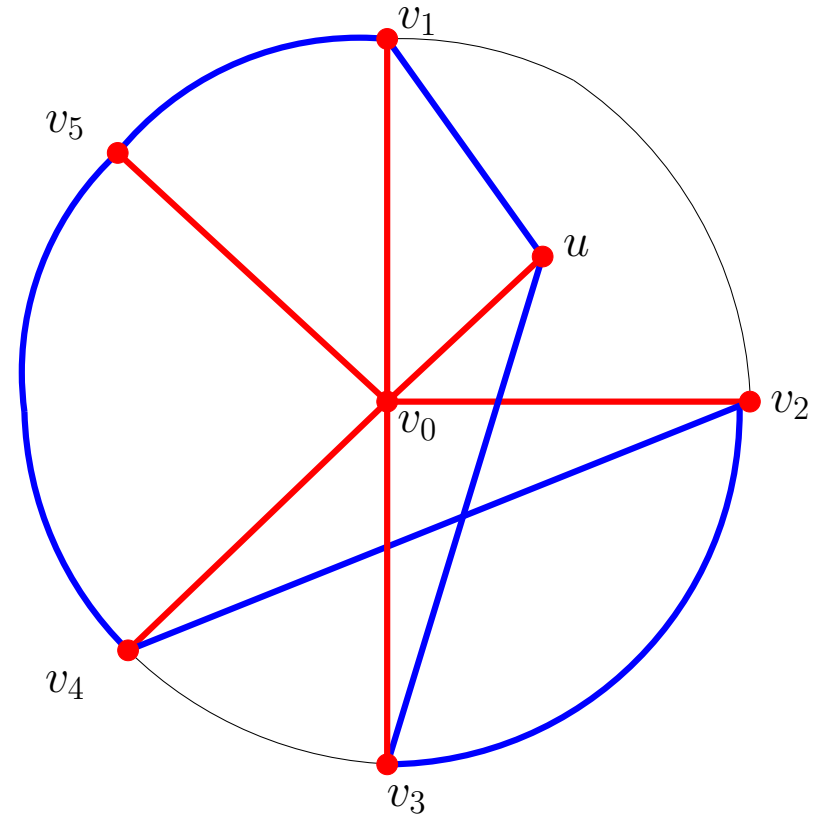
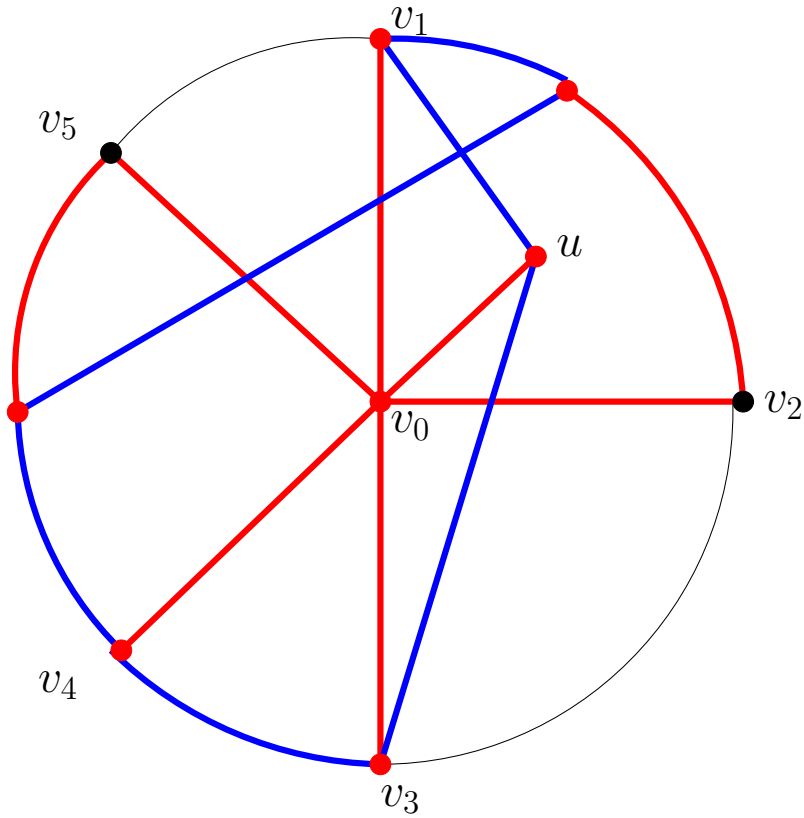
The program:

- constructs the various simple graphs that arise as cases in the proof, and
- tests each graph for the presence of a W_6 -subdivision.

Examples:

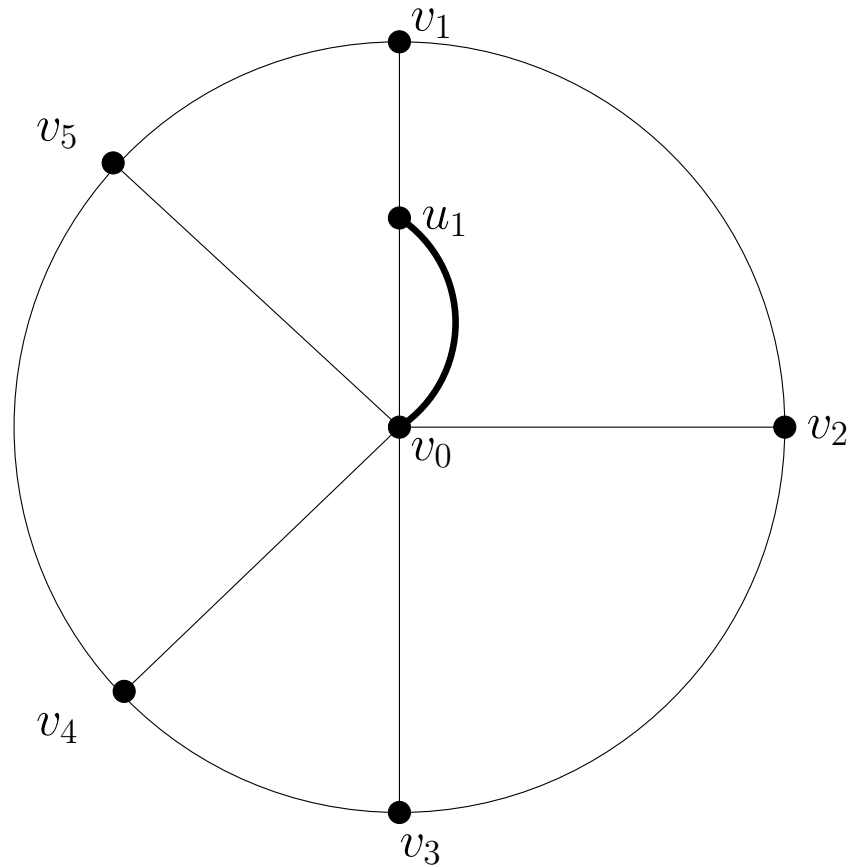


Examples:



- The program determines if a W_6 -subdivision is present by recursively testing all subgraphs obtained by removing a single edge from the input graph.
- Base cases are W_6 -subdivisions or graphs that have too few vertices or edges to contain such a subdivision.
- Naive algorithm; takes exponential time, but is sufficient for the small input graphs that arise as cases in the proof.
- Once the possibility of performing reductions and the presence of internal 3- and 4-edge-cutsets is eliminated, all resulting graphs are found to either:
 - contain a W_6 -subdivision; or
 - be topologically contained in Graph A.

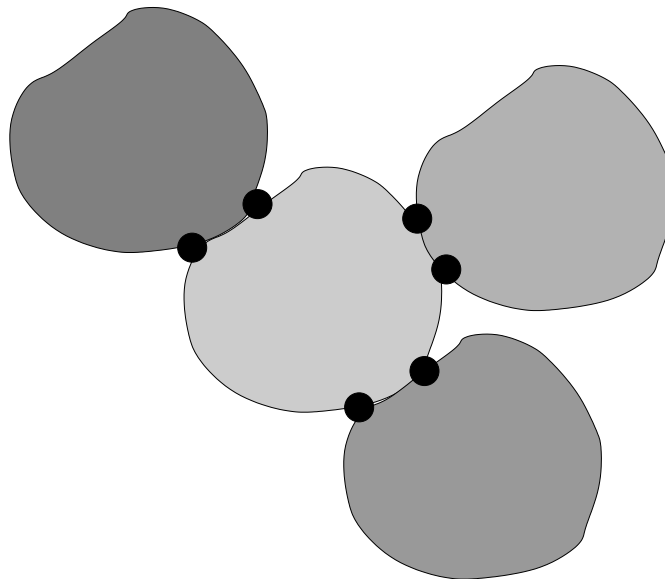
- (c) Path from v_0 to some vertex u_1 on one of the spokes of the W_5 -subdivision, such that this path that does not meet H except at its end points.



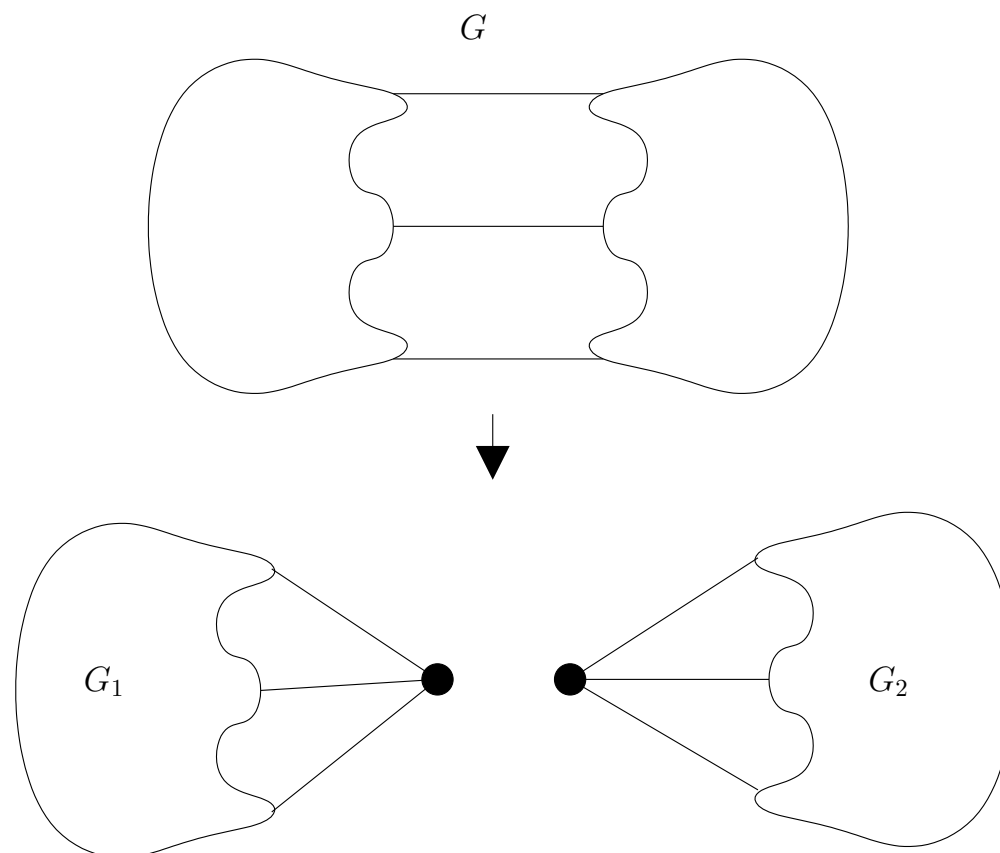
□

7 Using theorem to solve the topological containment problem for W_6

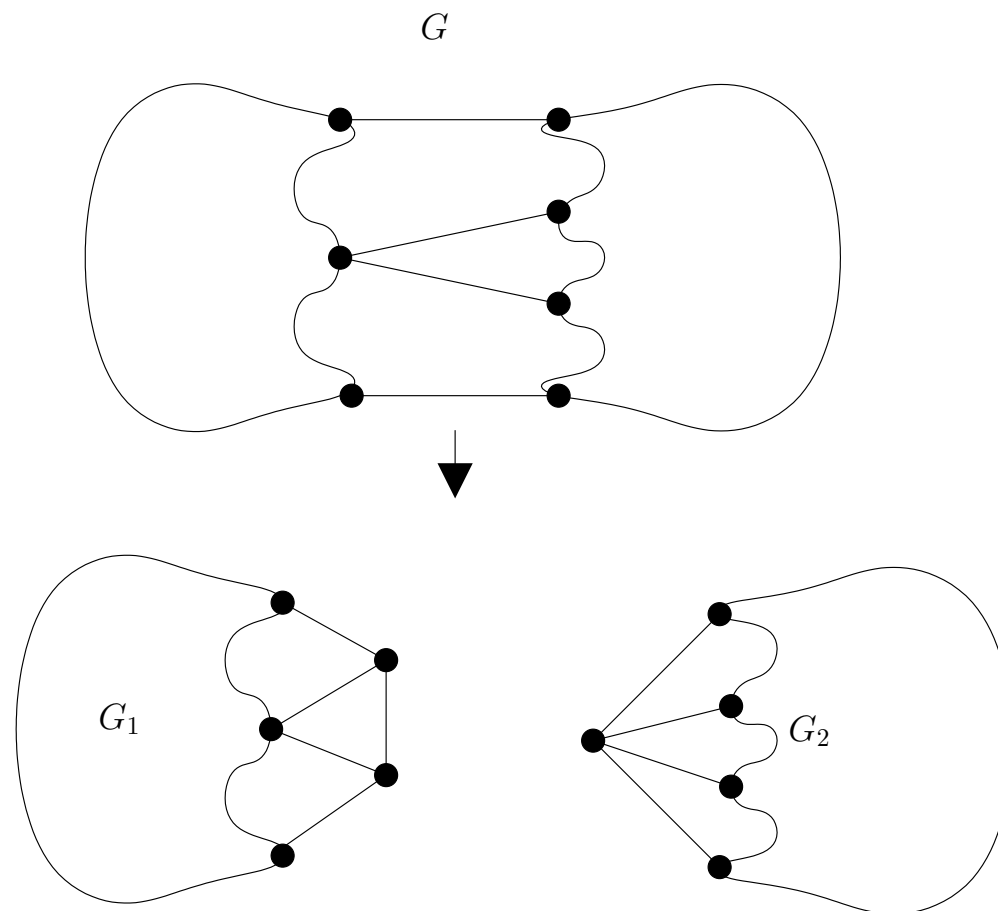
1. Find 3-connected components of G ; apply algorithm recursively to each component.



2. Separate G along its 3-edge cutsets; apply algorithm recursively to each component.

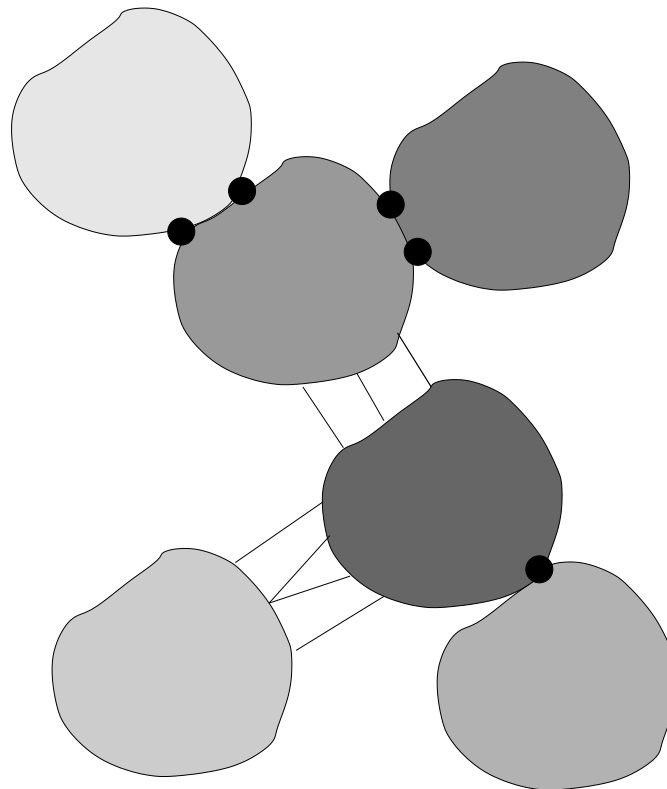


3. Separate G along its 4-edge-cutsets; apply algorithm recursively to each component.



4. If G is topologically contained in Graph A , G has no W_6 -subdivision; otherwise continue.
5. If some reduction R (either Reduction 1A or 2A) can be performed on G , let $G' = R(G)$. G contains a W_6 -subdivision iff G' does.
6. If G has no vertex of degree at least 6, G has no W_6 -subdivision. Otherwise, G contains a W_6 -subdivision.

Structure of 'reduced' graphs with no W_6 -subdivisions



8 Further results

- Result for W_6 strengthened and built on in similar way to obtain characterization for W_7
- As size of pattern graph H increases, so does the complexity of the characterization (and the proof!)

Theorem.

Let G be a 3-connected graph with at least 38 vertices. Suppose G has no internal 3 or 4-edge-cutsets, no internal $(1, 1, 1, 1)$ -cutsets, no type 1, 1a, 2, 2a, 3, 3a, 4, or 4a edge-vertex-cutsets, and is a graph on which Reductions 1A, 1B, 1C, 2A, 2B, 3, 4, 5, and 6 cannot be performed, for $k = 7$.

Then G has a W_7 -subdivision if and only if G contains some vertex v_0 of degree at least 7.

- Wheel with 8 spokes?
- General characterization for graphs with no W_k -subdivisions
- Techniques used may be useful in solving the topological containment problem for pattern graphs other than wheels, for example, K_5